

Geodesics

L, 10
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(M, ∇) manifold with an affine connection.

$\gamma: I \rightarrow M$ of class C^2 is called a geodesic for connection ∇ iff

$$\boxed{\frac{D}{dt}\left(\frac{d\gamma}{dt}\right) = \lambda \frac{d\gamma}{dt}} \quad \text{for some function } \lambda = \lambda(t) \text{ along } \gamma.$$

Recall
local expression

$$\frac{D}{dt}(V) = \left(\frac{dV^\mu}{dt} + \Gamma^\mu_{rs} V^r V^s \right) X_\mu$$

for $V = V^\mu(t) X_\mu$
vector fields along γ .

$$\frac{d\gamma}{dt} = \frac{dx^\mu}{dt} X_\mu, \quad X_\mu = \frac{\partial}{\partial x^\mu}$$

$\Rightarrow \frac{D}{dt}\left(\frac{d\gamma}{dt}\right) = \lambda \frac{d\gamma}{dt}$ can be locally written as

$$\boxed{\frac{d^2 x^\mu}{dt^2} + \Gamma^\mu_{rs} \frac{dx^r}{dt} \frac{dx^s}{dt} = \lambda \frac{dx^\mu}{dt}}$$

Reparametrization

$$t \rightarrow t' = f(t), \quad \begin{matrix} \circ \\ f \\ \parallel \\ f'(t) \neq 0 \end{matrix}$$

$$\frac{d}{dt} = \dot{f} \frac{d}{dt'}$$

$$\frac{d^2 x^\mu}{dt^2} = \frac{d}{dt} \left(\dot{f} \frac{dx^\mu}{dt'} \right) = \ddot{f} \frac{dx^\mu}{dt'} + \dot{f}^2 \frac{d^2 x^\mu}{dt'^2}$$

$$\ddot{f} \frac{dx^\mu}{dt'} + \dot{f}^2 \frac{d^2 x^\mu}{dt'^2} + \Gamma^\mu_{\nu\lambda} \dot{f}^2 \frac{dx^\nu}{dt'} \frac{dx^\lambda}{dt'} = \lambda \dot{f} \frac{dx^\mu}{dt'}$$

$$\frac{d^2 x^\mu}{dt'^2} + \Gamma^\mu_{\nu\lambda} \frac{dx^\nu}{dt'} \frac{dx^\lambda}{dt'} = \frac{\lambda \dot{f} - \ddot{f}}{\dot{f}^2} \frac{dx^\mu}{dt'}$$

$$\left| \frac{D}{dt'} \left(\frac{dx}{dt'} \right) = \lambda' \frac{dx}{dt'}, \quad \lambda' = \frac{\lambda \dot{f} - \ddot{f}}{\dot{f}^2} \right|$$

Note:

- 1) Definition does not depend on the choice of parametrization. If $t \rightarrow t' = f(t)$ then $\lambda \rightarrow \lambda' = \frac{\lambda \dot{f} - \ddot{f}}{\dot{f}^2}$
- 2) Given a geodesic with a parametrization for which we have function λ there exists a parametrization for which $\lambda' = 0$ ($\lambda \dot{f} = \ddot{f}$ has always solution).
- 3) This parametrization is called affine.

- 3) Affine parametrization is defined up to an affine transformation $t' \rightarrow at' + b$ $a \neq 0$.
 $\text{"const"}, b = \text{const.}$

$$(\lambda = 0 \Rightarrow \lambda' = \frac{-\ddot{f}}{\dot{f}^2} = 0 \Rightarrow f = at + b)$$

In affine parametrization ^{the} geodesic equation is

$$\left| \frac{d^2 x^\mu}{dt^2} + \Gamma^\mu_{\nu\lambda} \frac{dx^\nu}{dt} \frac{dx^\lambda}{dt} = 0 \right|$$

Observe that to determine a geodesic for a connection one needs only to know $\Gamma^\mu_{(rs)}$.

Indeed:

$$\Gamma^\mu_{rs} \frac{dx^r}{dt} \frac{dx^s}{dt} = \left(\Gamma^\mu_{(rs)} + \cancel{\Gamma^\mu_{[rs]}} \right) \frac{dx^r}{dt} \frac{dx^s}{dt}$$

↖ sym.
↗ antisym.

$$\Gamma^\mu_{rs} = \underbrace{\frac{1}{2}(\Gamma^\mu_{rs} + \Gamma^\mu_{sr})}_{\Gamma^\mu_{(rs)}} + \underbrace{\frac{1}{2}(\Gamma^\mu_{rs} - \Gamma^\mu_{sr})}_{\Gamma^\mu_{[rs]}}$$

Corollary

There are different connections that have the same geodesics!

(add smth antisymmetric $\downarrow$ to Γ^μ_{rs} in $\Gamma^\mu_{(rs)}$)

How to determine connection?

Recall: $\nabla_\mu X_\nu = \Gamma^\rho_{\mu\nu} X_\rho$, $[X_\rho, X_\sigma] = C^\mu_{\rho\sigma} X_\mu$

$$\begin{aligned} T(X_\mu, X_\nu) &= \nabla_\mu X_\nu - \nabla_\nu X_\mu - [X_\mu, X_\nu] = \\ &= (\Gamma^\rho_{\mu\nu} - \Gamma^\rho_{\nu\mu} - C^\rho_{\mu\nu}) X_\rho = Q^\rho_{\mu\nu} X_\rho \end{aligned}$$

$$\Rightarrow \Gamma^\rho_{\mu\nu} - \Gamma^\rho_{\nu\mu} = C^\rho_{\mu\nu} + Q^\rho_{\mu\nu}$$

$$\boxed{\Gamma^\rho_{[\mu\nu]} = \frac{1}{2} C^\rho_{\mu\nu} + \frac{1}{2} Q^\rho_{\mu\nu}} \quad (AS)$$

Corollary

- 1) Antisymmetric part of the connection is determined by the torsion and the anholonomy coefficients.

$$\boxed{\Gamma^{\rho}_{\nu\mu} = \Gamma^{\rho}_{(\nu\mu)} + \frac{1}{2} C^{\rho}_{\mu\nu} + \frac{1}{2} Q^{\rho}_{\mu\nu}}$$

- 2) Torsionless connection in holonomic frame is symmetric.

(Pseudo) Riemannian connections

(M, g) . It is natural to look for a connection ∇ which preserves the metric:

$$\nabla_X g = 0 \quad \forall X \in \mathfrak{X}(M)$$

$$\Rightarrow g = g_{\mu\nu} \theta^{\mu} \theta^{\nu} \quad \text{where} \quad \theta^{\mu} \theta^{\nu} = \frac{1}{2} (\theta^{\mu} \otimes \theta^{\nu} + \theta^{\nu} \otimes \theta^{\mu})$$

$$X_{\mu} \lrcorner \theta^{\nu} = \delta_{\mu}^{\nu}$$

$$0 = \nabla_{\mu} g_{rs} = X_{\mu}(g_{rs}) - \Gamma^{\alpha}_{r\mu} g_{\alpha s} - \Gamma^{\alpha}_{s\mu} g_{r\alpha} \quad | \cdot \theta^{\mu}$$

$$\boxed{0 = Dg_{rs} = dg_{rs} - g_{s\alpha} \Gamma^{\alpha}_r - g_{r\alpha} \Gamma^{\alpha}_s} \quad (Mc)$$

Digression

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Assumption about the nondegeneracy of g

$$g(X, Y) = 0 \quad \forall Y \Rightarrow X = 0 \text{ means that}$$

at every point the map:

$$T_p M \ni X_p \longrightarrow g_p(X_p, \cdot) \in T_p^* M$$

is isomorphism of vector spaces $T_p M$ and $T_p^* M$.

Using the metric (even is Riemannian case!)

we can identify TM and T^*M .

In the old tensorial language:

(i) V^μ — coefficients of a vector field V

$$V^\mu \xrightarrow{g_{\mu\nu}} g_{\mu\nu} V^\nu = V_\nu \leftarrow \text{coefficients of a 1-form}$$

(ii) λ_μ — coefficients of a 1-form λ

$g_{\mu\nu}$ is invertible $\Rightarrow g^{\alpha\beta}$ s.t. $g^{\alpha\beta} g_{\beta\mu} = \delta^\alpha_\mu$
is uniquely defined by g .

$$\lambda_\mu \xrightarrow{g^{\mu\nu}} g^{\mu\nu} \lambda_\nu = \lambda^\nu \leftarrow \text{coefficients of a vector field.}$$

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Our condition ^(MC) for a connection that preserves the metric

$$dg_{rs} = \Gamma_{sv} + \Gamma_{vs} \quad \text{or}$$

$$\boxed{\Gamma_{sv\mu} + \Gamma_{vs\mu} = X_\mu(g_{rs})} \quad (1)$$

We also have:

$$\boxed{\Gamma_{sv\mu} - \Gamma_{s\mu v} = C_{\mu\nu}^s + Q_{\mu\nu}^s} \quad (2)$$

(1) - (2):

$$\Gamma_{sv\mu} + \Gamma_{s\mu v} = X_\mu(g_{rs}) - C_{\mu\nu}^s - Q_{\mu\nu}^s =: H_{rs\mu}$$

$$\begin{array}{l}
 + \left| \begin{array}{l} \underline{\Gamma_{rs\mu}} + \underline{\Gamma_{s\mu v}} = H_{rs\mu} \\ \underline{\Gamma_{\mu rs}} + \underline{\Gamma_{vs\mu}} = H_{\mu rs} \\ \underline{\Gamma_{s\mu v}} + \underline{\Gamma_{\mu v s}} = H_{s\mu v} \end{array} \right.
 \end{array}$$

$$2\Gamma_{rs\mu} = H_{rs\mu} + H_{\mu rs} - H_{s\mu v}$$

$$\left\{ \begin{array}{l} \boxed{\Gamma_{rs\mu} = \frac{1}{2}(H_{rs\mu} + H_{\mu rs} - H_{s\mu v})} \\ \boxed{H_{rs\mu} = X_\mu(g_{rs}) - C_{\mu\nu}^s - Q_{\mu\nu}^s} \end{array} \right. \quad \text{where}$$